

MATH 20D Spring 2023 Lecture 24.

Systems in Normal Form, Eigenvalue, and Eigenvectors.

- CAPE course and professor evaluations are available. Please fill this out BEFORE 8am on June 10th.

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- Midterm 2 grades are available, regrade request window closing tonight.
- HW 4 grades available, regrade request window closing Sunday 11:59pm.

- 1 Linear Systems in Normal Form
- 2 Eigenvalues and Eigenvectors

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2 Eigenvalues and Eigenvectors

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$$y'(t) = \frac{1}{3}x(t) - \frac{1}{3}y(t)$$

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(ii) Higher order ODE's give first order system of ODE's

Let $x_1(t) = y(t)$, $x_2(t) = y'(t)$, and $x_3(t) = y''(t)$. Then the third order ODE

$$y'''(t) + 2y''(t) + y'(t) = 0 \tag{1}$$

is equivalent to the first order system of ODE's

$$x_1'(t) = x_2(t)$$

$$x_2'(t) = x_3(t)$$

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- If we introduce the **vector valued function** $\mathbf{x}(t) = \text{col}(x_1(t), x_2(t), x_3(t))$ then the system can be written in **matrix notation**

$$\mathbf{x}'(t) = A\mathbf{x}(t).$$

Example

Rewrite each of the systems below as a first order equation in matrix notation

(a) $y'' + 2y' + 3y = \frac{1}{t}$ (b) $ty'' + (1 - t)y = e^t$ (c) $\begin{aligned} 2x'' + 6x - 2y &= 0 \\ y'' + 2y - 2x &= 0 \end{aligned}$

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Definition

A system of differential equation is in **normal form** if it is expressed as

$$\mathbf{x}'(t) = \mathbf{A}(t)\mathbf{x}(t) + \mathbf{f}(t) \quad (2)$$

where $\mathbf{x}(t) = \text{col}(x_1(t), \dots, x_n(t))$ and $\mathbf{f}(t) = \text{col}(f_1(t), \dots, f_n(t))$.

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- We say that (2) is **homogeneous** if $\mathbf{f}(t) \equiv 0$.
- Say that (2) has **constant coefficients** if $\mathbf{A}(t) = \mathbf{A}$ has constant entries.

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Leading Questions

Suppose A is a 2×2 matrix with constant entries.

- How do we write down a general solutions to the equation

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- How do we solve the initial value problem

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If $a \neq 0$, b , and c are constant then the IVP

$$ay'' + by' + cy = 0, \quad y(0) = Y_0, \quad y'(0) = Y_1$$

is given in matrix notation as $\mathbf{x}'(t) = \begin{pmatrix} 0 & 1 \\ -c/a & -b/a \end{pmatrix} \mathbf{x}(t)$, $\mathbf{x}(0) = \text{col}(Y_0, Y_1)$.

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Defining Eigenvalues and Eigenvectors

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- Write

$$\mathbb{R}^n = \{\text{col}(x_1, \dots, x_n) : x_1, \dots, x_n \in \mathbb{R}\}.$$

so that multiplication by A gives a function $\mathbf{v} \mapsto A\mathbf{v}$ from \mathbb{R}^n to \mathbb{R}^n .

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Example

Show that $\mathbf{v} = \begin{pmatrix} 3 \\ 1 \end{pmatrix}$ is an eigenvector of $A = \begin{pmatrix} 2 & -3 \\ 1 & -2 \end{pmatrix}$ with eigenvalue $\lambda = 1$.

Example

- Show that

$$\mathbf{v} = \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix}$$

is an eigenvector of $A = \begin{pmatrix} 1 & -2 & 2 \\ -2 & 1 & 2 \\ 2 & 2 & 1 \end{pmatrix}$ with eigenvalue $\lambda = 3$.

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- The above equation admits a non-zero solution if and only if $A - \lambda I$ is **not** invertible.
- Recall that a 2-by-2 matrix $\begin{pmatrix} a & b \\ c & d \end{pmatrix}$ is **invertible** if and only if the determinant $\begin{vmatrix} a & b \\ c & d \end{vmatrix} = ad - bc$ is non-zero.

Summary

- Given a 2-by-2 matrix A . We can solve for the eigenvalues of A by solving the **characteristic equation**

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Example

Find the eigenvalues and eigenvectors of the matrices below

$$\text{(a)} \quad A = \begin{pmatrix} 2 & 1 \\ 1 & 2 \end{pmatrix} \qquad \text{(b)} \quad A = \begin{pmatrix} 1 & 2 \\ 0 & 1 \end{pmatrix}$$